MATH 221, FINAL EXAM (9:30), SUMMER 008

AYMAN BADAWI

QUESTION 1. (15 points) (Write DOWN T OR F)

- (1) If V is an eigenvector of a matrix $n \times n$ A, then V is also an eigenvector of A^3 .
- (2) If A is 4×3 , then the homogeneous system AX = 0 has infinitely many solutions.
- (3) If A is nonsingular, 3×3 , then the reduced echelon form of A is I_3 .
- (4) If A is a 3×5 matrix such that Nullity(A) = 2, then for every column matrix 3×1 b the system AX = b has infinitely many solutions.
- (5) If 2 is an eginvalue of a 4×4 matrix A, then the matrix $A 2I_4$ is singular.
- (6) If A is a 4×4 matrix, then det(3A) = 3det(A).
- (7) If 7 is an eigenvalue of an $n \times n$ matrix A, then $\frac{1}{7}$ is an eigenvalue of A^T .
- (8) If A is an 3×3 matrix and $A = A^{-1}$, then $A^3 = A$
- (9) If A is nonsingular, then A^T is nonsingular.
- (10) At this minute, you are in Nab 10.

QUESTION 2. (5 points) Find the matrix 2×2 A such that $\begin{pmatrix} A \begin{bmatrix} 3 & 2 \\ 1 & 1 \end{bmatrix} \end{pmatrix}^{-1} = A^{-1} + 2I_2$

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QUESTION 3. (12 points) Let $A\begin{bmatrix} 3 & 0 & -2 \\ -2 & 2 & 4 \\ 1 & 0 & 0 \end{bmatrix}$ For each eigenvalue of A find the corresponding eigenspace. If A is diagnolizable, then find a diagonal metric D and a parameter wetrin A is diagnolizable.

diagonal matrix D, and a nonsingular matrix Q such that $Q^{-1}AQ = D$.

QUESTION 4. Given $T: \mathbb{R}^3 \longrightarrow \mathbb{R}^4$ is a linear transformation such that $T\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right) = \begin{bmatrix}1\\2\\-1\\1\end{bmatrix}$, $T\left(\begin{bmatrix}0\\1\\0\end{bmatrix}\right) = \begin{bmatrix}2\\4\\-2\\2\end{bmatrix}$, and $T\left(\begin{bmatrix}1\\1\\1\end{bmatrix}\right) = \begin{bmatrix}4\\8\\3\\4\end{bmatrix}$ a) (5 points) Find $T\left(\begin{bmatrix}0\\0\\1\end{bmatrix}\right)$

b) (8 points) Find the standard matrix representation of T. Then find a basis for Ker(T), and a basis for Range(T).

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QUESTION 5. (6 points) Let $A = \begin{bmatrix} 2 & -2 & 3 \\ -1 & 0 & -1 \\ 1 & 1 & 1 \end{bmatrix}$. Find A^{-1} , and find $(A^T)^{-1}$.

QUESTION 6. Given $A \xrightarrow[R_1 \leftrightarrow R_2]{} A_1 \xrightarrow[16R_2]{} A_2 \xrightarrow[-R_1 + R_3 \rightarrow R_3]{} A_3 = \begin{bmatrix} 2 & 3 & 4 \\ 0 & 4 & -3 \\ 0 & 0 & 6 \end{bmatrix}$. *a)*(4 points) Find det(2A).

b)(5 points) Write A as product of elementary matrices with A_3 .

QUESTION 7. a) (5 points) $D = \{f(x) \in P_4 \mid f'(0) = 0, f(1) = 0\}$ is subspace of P_4 (DO NOT SHOW THAT). Find a basis for D.

b)(5 points) $L = \{A \in M_{3\times 2}(R) \mid a_{21} + a_{22} + a_{31} = 0\}$ is a subspace of $M_{3\times 2}(R)$ (DO NOT SHOW THAT). Find a basis for L.

c) (5 points) Let $M = span\{1 + x, -1 + 2x, x^2, 3x + x^2\}$. Find a basis for M.

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QUESTION 8. a) (6 points) Use CRAMER RULE to solve for x_3

 $\begin{aligned} x_1 + x_2 + x_3 &= 12 \\ -x_1 + x_2 - x_3 &= -10 \\ -5x_1 + -5x_2 + 2x_3 &= 10 \end{aligned}$

b)(6 points) Let $A = \begin{bmatrix} a & 3 & 1 \\ b & 5 & 2 \\ c & 1 & 3 \end{bmatrix}$ and the REDUCED ECHELON FORM OF A IS the MATRIX $\begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$. Find a, b, c (SHOW THE WORK....GUESSING IS NOT ACCEPTABLE)

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QUESTION 9. a/(7 points) Solve the following system

 $x_1 + 4x_2 + 3x_3 - x_4 + x_5 = 2$ -x₁ - 3x₂ - 3x₃ + x₄ + x₅ = -4 2x₁ + 8x₂ + 6x₃ - x₄ + 3x₅ = -2

b) (6 points) Let $D = Span\{1, 0, 1, 2\}, (1, 1, 0, 0), (1, 0, -1, -1)\}$. Find an ORTHOGONAL BASIS for D.

DEPARTMENT OF MATHEMATICS & STATISTICS, AMERICAN UNIVERSITY OF SHARJAH, P.O. BOX 26666, SHARJAH, UNITED ARAB EMIRATES, WWW.AYMAN-BADAWI.COM *E-mail address:* abadawi@aus.edu